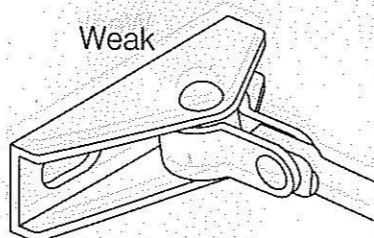


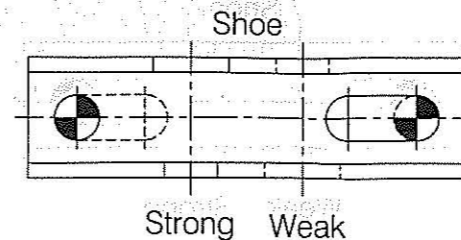
Strong

Position 1 force 3
Position 2 force 4



Weak

Position 1 force 2
Position 2 force 3



Shoe

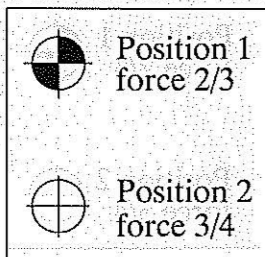
Strong Weak

DETERMINE POSITION OF SHOE FROM CHART OPPOSITE AND FIX ACCORDINGLY

UNDERSIDE OF FRAME

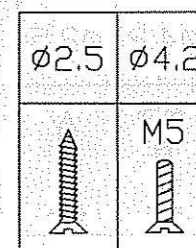
SET TO TOP OF DOOR

Speed Adjusting Valve



Use this side of template for clockwise opening door (RIGHT HAND OPENING DOOR)

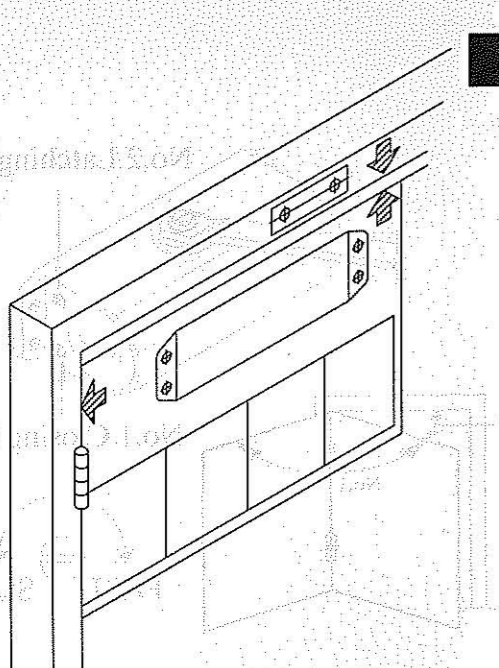
6-M5*P0.8



HINGE EDGE OF DOOR

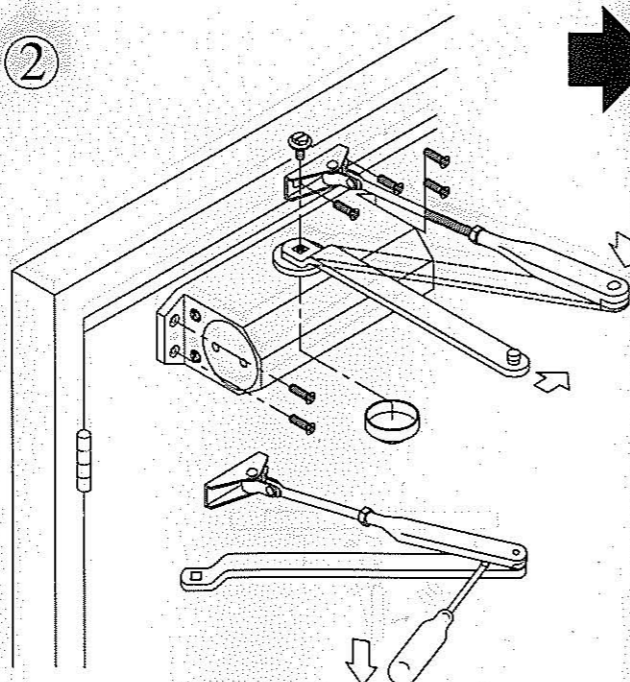
(Position 1) force 2/3 90mm
(Position 2) force 3/4 110mm

①



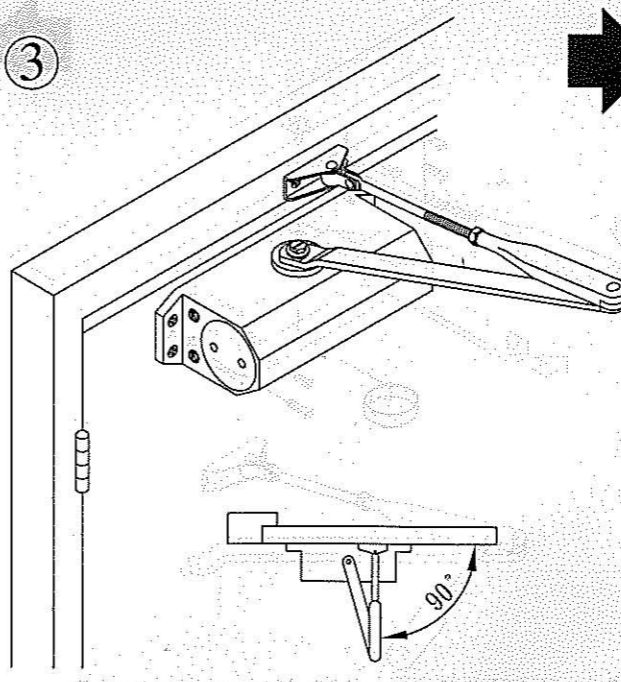
"Determine opening degree requirements 105 or 180 degrees, then select power requirement. This can be located on the template. Then use template to mark holes for closer body and arm pivot bracket"

②



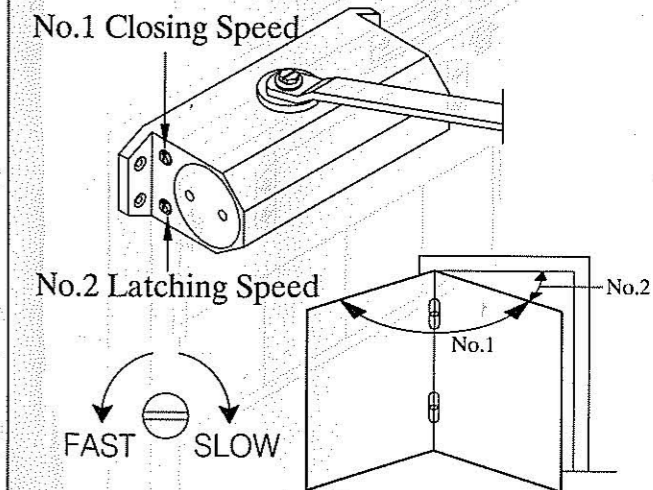
"Arm pivot bracket assembly into position and fix closer body to the marked holes ensuring that you select the position of the shoe, on the face of the frame, in the correct direction" Refer weak or strong.

③



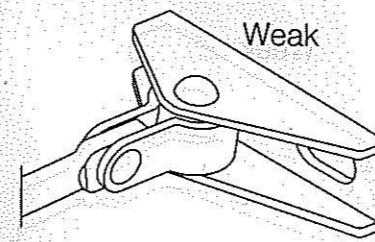
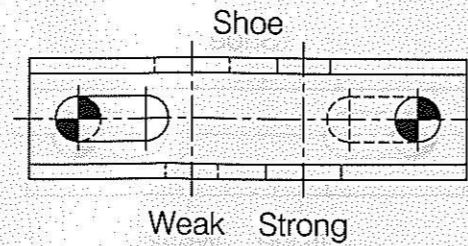
Standard drawing

④

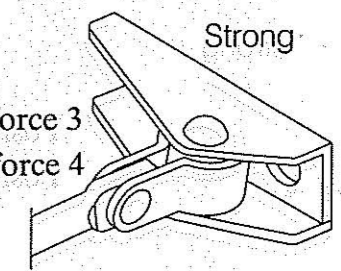


Adjust speed

17-1 DETERMINE POSITION OF SHOE FROM CHART OPPOSITE AND FIX ACCORDINGLY



Position 1 force 2
Position 2 force 3

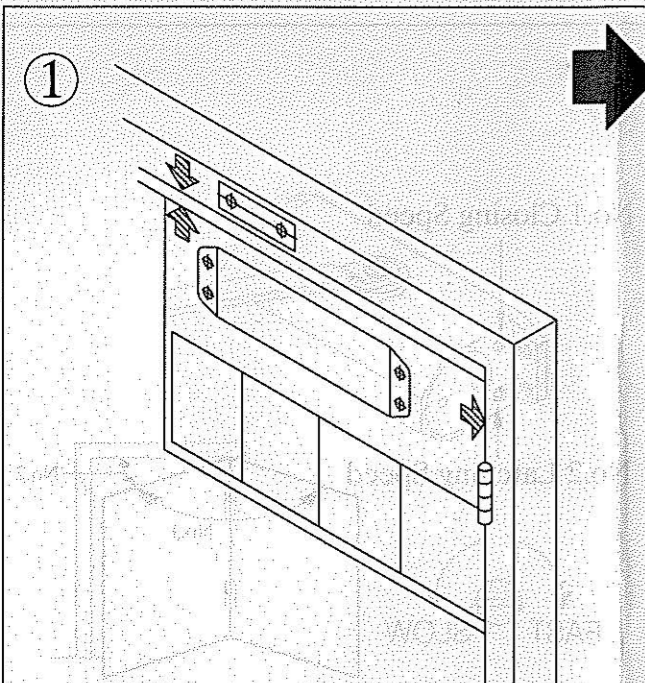
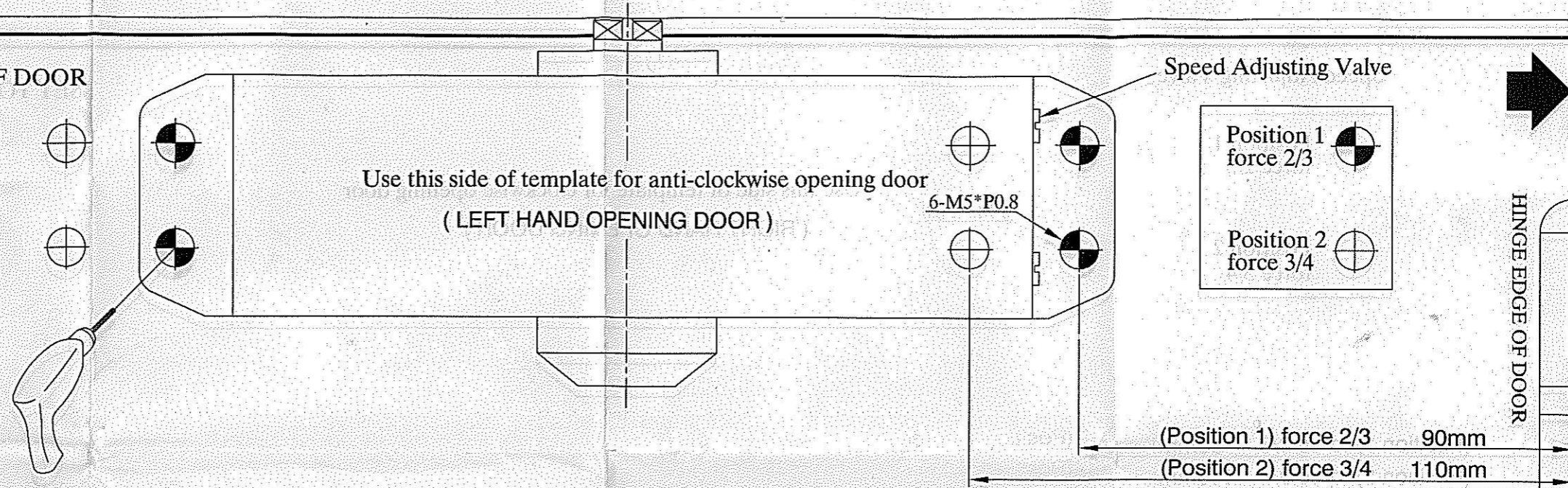


Position 1 force 3
Position 2 force 4

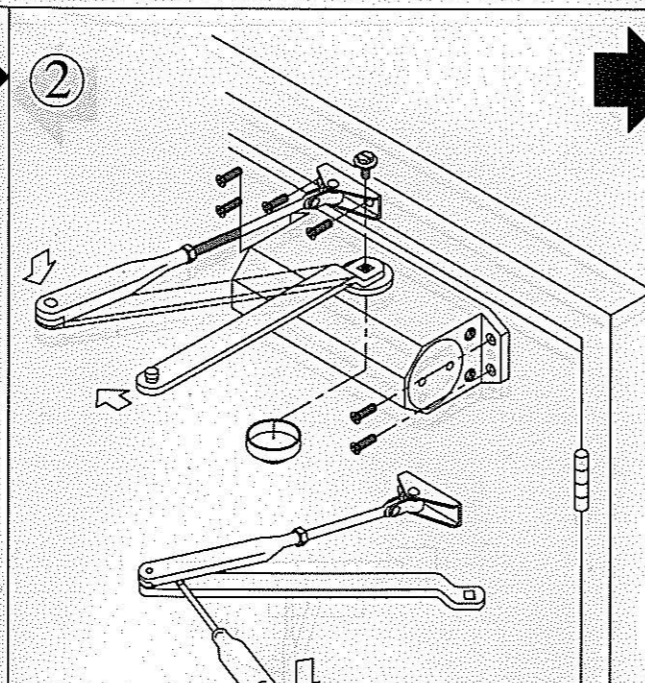
UNDERSIDE OF FRAME

SET TO TOP OF DOOR

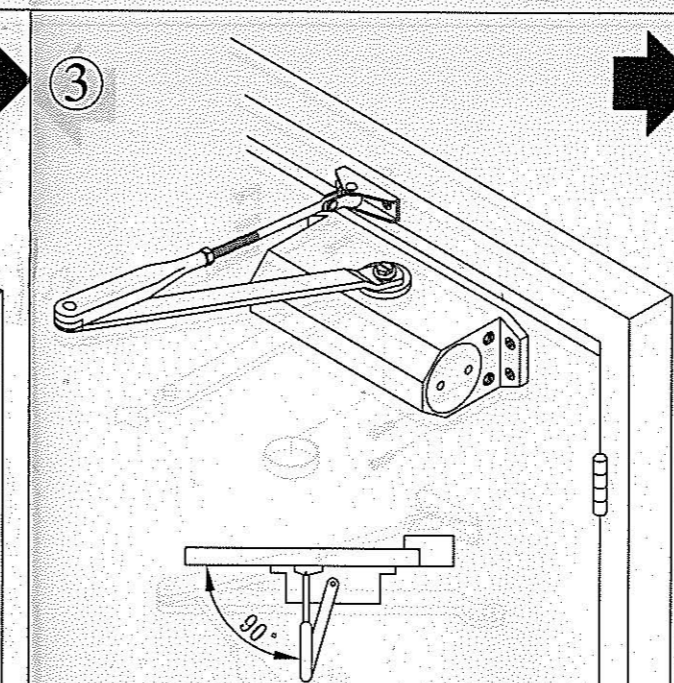
∅4.2	∅2.5
M5	



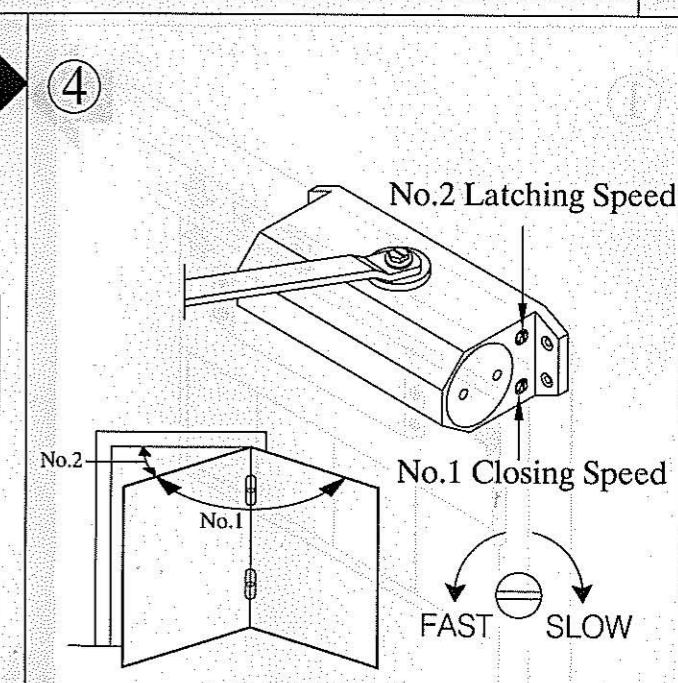
"Determine opening degree requirements 105 or 180 degrees, then select power requirement. This can be located on the template. Then use template to mark holes for closer body and arm pivot bracket"



"Arm pivot bracket assembly into position and fix closer body to the marked holes ensuring that you select the position of the shoe, on the face of the frame, in the correct direction" Refer weak or strong.



Standard drawing



Adjust speed